# Existence of Riemannian metrics with positive biorthogonal curvature on simply connected 5 -manifolds 

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#### Abstract

Using the recent work of Bettiol, we show that a first-order conformal deformation of Wilking's metric of almost-positive sectional curvature on $S^{2} \times S^{3}$ yields a family of metrics with strictly positive average of sectional curvatures of any pair of 2-planes that are separated by a minimal distance in the 2-Grassmanian. A result of Smale allows us to conclude that every closed simply connected 5 -manifold with torsion-free homology and trivial second Stiefel-Whitney class admits a Riemannian metric with a strictly positive average of sectional curvatures of any pair of orthogonal 2-planes.


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1. Introduction and main results. Let $(M, g)$ be a compact Riemannian $n$ manifold and let $\mathrm{sec}_{g}$ be the sectional curvature of the metric. We often abuse notation and denote the Riemannian metric by $(M, g)$ as well. For each 2-plane

$$
\begin{equation*}
\sigma \in \operatorname{Gr}_{2}\left(T_{p} M\right)=\left\{X \wedge Y \in \Lambda^{2} T_{p} M:\|X \wedge Y\|^{2}=1\right\} \tag{1.1}
\end{equation*}
$$

let $\sigma^{\perp} \subset T_{p} M$ be its orthogonal complement. That is, there is a $g$-orthogonal direct sum decomposition $\sigma \oplus \sigma^{\perp}=T_{p} M$ at a point $p \in M$.

Definition 1. The biorthogonal curvature of a 2-plane $\sigma \in \operatorname{Gr}_{2}\left(T_{p} M\right)$ is

$$
\begin{equation*}
\sec _{g}^{\perp}(\sigma):=\min _{\substack{\sigma^{\prime} \in \operatorname{Gr}_{2}\left(T_{p} M\right) \\ \sigma^{\prime} \subset \sigma^{\perp}}} \frac{1}{2}\left(\sec _{g}(\sigma)+\sec _{g}\left(\sigma^{\prime}\right)\right) \tag{1.2}
\end{equation*}
$$

(cf. [3, Section 5.4]). We say that $(M, g)$ has positive biorthogonal curvature $\sec _{g}^{\perp}>0$ if (1.2) is positive for every $\sigma \in \operatorname{Gr}_{2}\left(T_{p} M\right)$ at every point $p \in M$.

A stronger curvature condition is the following. Choose a distance on the Grassmanian bundle $\mathrm{Gr}_{2}(T M)$ that induces the standard topology.
Definition 2. The distance curvature of a 2-plane $\sigma \subset T_{p} M$ is

$$
\begin{equation*}
\sec _{g}^{\theta}(\sigma):=\min _{\substack{\sigma^{\prime} \in \operatorname{Gr}_{2}\left(T_{p} M\right) \\ \operatorname{dis}\left(\sigma, \sigma^{\prime}\right) \geq \theta}} \frac{1}{2}\left(\sec _{g}(\sigma)+\sec _{g}\left(\sigma^{\prime}\right)\right) \tag{1.3}
\end{equation*}
$$

for each $\theta>0$ (cf. [3, Section 5.2]). We say that $\left(M, g^{\theta}\right)$ has positive distance curvature $\sec _{g^{\theta}}>0$ if for every $\theta>0$, there is a Riemannian metric $\left(M, g^{\theta}\right)$ for which (1.3) is positive for every $\sigma \in \operatorname{Gr}_{2}\left(T_{p} M\right)$ at every point $p \in M$.

Bettiol [4] classified up to homeomorphism closed simply connected 4manifolds that admit a Riemannian metric of positive biorthogonal curvature by constructing metrics of positive distance curvature on $S^{2} \times S^{2}$ [2, Theorem, Proposition 5.1], [3, Theorem 6.1], and showing that positive biorthogonal curvature is a property that is closed under connected sums [3, Proposition 7.11], [4, Proposition 3.1].

In this paper, we extend Bettiol's results to dimension five. More precisely, we build upon Bettiol's work and show that an application of a first-order conformal deformation to Wilking's metric ( $S^{2} \times S^{3}, g_{W}$ ) of almost-positive sectional curvature [11] yields the main result of this note.
Theorem A. For every $\theta>0$, there is a Riemannian metric $\left(S^{2} \times S^{3}, g^{\theta}\right)$ such that
(a) $\sec _{g^{\theta}}^{\theta}>0$;
(b) there is a limit metric $g^{0}$ such that $g^{\theta} \rightarrow g^{0}$ in the $C^{k}$-topology as $\theta \rightarrow 0$ for $k \geq 0$;
(c) $g^{\theta}$ is arbitrarily close to Wilking's metric $g_{W}$ of almost-positive curvature in the $C^{k}$-topology for $k \geq 0$;
(d) $\operatorname{Ric}_{g^{\theta}}>0$;
(e) there is a 2-plane $\sigma \in \operatorname{Gr}_{2}\left(T_{p} S^{2} \times S^{3}\right)$ with $\sec _{g^{\theta}}(\sigma)<0$;

In particular, there is a Riemannian metric of positive biorthogonal curvature on $S^{2} \times S^{3}$.

The next corollary is a consequence of coupling Theorem A with a classification result of Smale [8].
Corollary B. Every closed simply connected 5-manifold with torsion-free homology and zero second Stiefel-Whitney class admits a Riemannian metric of positive biorthogonal curvature.

The hypothesis imposed on the homology and the second Stiefel-Whitney class of the manifolds of Corollary B are technical in nature; cf. Remark 2. Indeed, an examination of the canonical metric on the Wu manifold yields the following proposition.
Proposition C. The symmetric space metric $(\mathrm{SU}(3) / \mathrm{SO}(3), g)$ has positive biorthogonal curvature.

The Wu manifold has second homology group of order two and nontrivial second Stiefel-Whitney class.

## 2. Constructions of Riemannian metrics of positive biorthogonal curvature.

2.1. Wilking's metric of almost-positive curvature on $S^{2} \times S^{3}$. We follow the exposition in [11, Section 5] to describe Wilking's construction of a metric of almost-positive curvature on the product of projective spaces $\mathbb{R} P^{2} \times \mathbb{R} P^{3}$ and its pullback to $S^{2} \times S^{3}$ under the covering map; see [12, Section 5] for a discussion relating these two constructions.

The unit tangent sphere bundle of the 3 -sphere

$$
\begin{equation*}
T_{1}\left(S^{3}\right)=S^{2} \times S^{3} \tag{2.1}
\end{equation*}
$$

embeds into $\mathbb{R}^{4} \times \mathbb{R}^{4}=\mathbb{H} \times \mathbb{H}$ as a pair of orthogonal unit quaternions

$$
\begin{equation*}
S^{3} \times S^{2}=\{(p, v) \in \mathbb{H} \times \mathbb{H}:|p|=|v|=1,\langle p, v\rangle=0\} \subset \mathbb{H} \times \mathbb{H}, \tag{2.2}
\end{equation*}
$$

where $\langle x, y\rangle=\operatorname{Re}(\bar{x} y),|x|^{2}=\langle x, x\rangle$, and $\bar{x}$ denotes the quarternion conjugation of $x$. The group $G=\operatorname{Sp}(1) \times \operatorname{Sp}(1) \simeq S^{3} \times S^{3}$ acts on $S^{2} \times S^{3}$ by

$$
\begin{equation*}
\left(q_{1}, q_{2}\right) \star(p, v)=\left(q_{1} p \bar{q}_{2}, q_{1} v \bar{q}_{2}\right) \tag{2.3}
\end{equation*}
$$

for $q_{1}, q_{2} \in \operatorname{Sp}(1)$ and $(p, v) \in S^{2} \times S^{3}$. This action is effectively free and transitive. The isotropy group of the point $(1, i) \in S^{2} \times S^{3}$ is

$$
\begin{equation*}
H=\left\{\left(e^{i \phi}, e^{i \phi}\right) \in \operatorname{Sp}(1) \times \operatorname{Sp}(1)\right\} \subset G \tag{2.4}
\end{equation*}
$$

Thus, $S^{2} \times S^{3} \simeq G / H$ is a homogeneous space.
In order to put a metric on $S^{2} \times S^{3}$, Wilking first defines a left invariant metric $g$ on $G=\operatorname{Sp}(1) \times \operatorname{Sp}(1)$ as follows. Let

$$
\begin{equation*}
g_{0}\left((X, Y),\left(X^{\prime}, Y^{\prime}\right)\right)=\langle X, Y\rangle+\left\langle X^{\prime}, Y^{\prime}\right\rangle \tag{2.5}
\end{equation*}
$$

for $(X, Y),\left(X^{\prime}, Y^{\prime}\right) \in \mathfrak{s p}(1) \oplus \mathfrak{s p}(1)=\operatorname{Im}(\mathbb{H}) \oplus \operatorname{Im}(\mathbb{H})$, denote a bi-invariant metric. In terms of $g_{0}$, the metric $g$ is

$$
\begin{equation*}
g\left((X, Y),\left(X^{\prime}, Y^{\prime}\right)\right)=g_{0}\left(\Phi(X, Y),\left(X^{\prime}, Y^{\prime}\right)\right) \tag{2.6}
\end{equation*}
$$

where $\Phi$ is a $g_{0}$-symmetric, positive definite endomorphism of $\mathfrak{s p}(1) \oplus \mathfrak{s p}(1)$ given by

$$
\begin{equation*}
\Phi=\operatorname{Id}-\frac{1}{2} P \tag{2.7}
\end{equation*}
$$

and $P$ is the $g_{0}$-orthogonal projection onto the diagonal subalgebra

$$
\begin{equation*}
\Delta \mathfrak{s p}(1) \subset \mathfrak{s p}(1) \oplus \mathfrak{s p}(1) ; \tag{2.8}
\end{equation*}
$$

see [11, p. 125].
Wilking's doubling trick guarantees the existence of a diffeomorphism

$$
\begin{equation*}
G / H \simeq \Delta G \backslash G \times G /\left\{1_{G}\right\} \times H \tag{2.9}
\end{equation*}
$$

where $\Delta G \backslash$ denotes the quotient by the left diagonal action of $G$ on $G \times G$ and $H$ acts on the second factor from the right. Consider the product $(G \times G, g+g)$ (cf. (2.6)) and the induced metric on $S^{2} \times S^{3} \simeq \Delta G \backslash G \times G /\left\{1_{G}\right\} \times H$ that we denote by $g_{W}$. That is, Wilking's metric $\left(S^{2} \times S^{3}, g_{W}\right)$ is the metric that makes the quotient submersion

$$
\begin{equation*}
(G \times G, g \oplus g) \rightarrow\left(\Delta G \backslash G \times G /\left\{1_{G}\right\} \times H, g_{W}\right) \tag{2.10}
\end{equation*}
$$

into a Riemannian submersion. Wilking has shown that $\left(S^{2} \times S^{3}, g_{W}\right)$ has almost-positive curvature, with flat 2-planes located on two hypersurfaces. These hypersurfaces are both diffeomorphic to $S^{2} \times S^{2}$, and they intersect along an $\mathbb{R} P^{3}[11$, Corollary 3, Proposition 6]. However, except for points that lie on four disjoint copies of $S^{2}$ inside these two hypersurfaces, there is a unique flat 2-plane. At each point in these four 2 -spheres, there is a one parameter family of flat 2-planes and neither the distance curvature nor the biorthogonal curvature of the metric $g_{W}$ are strictly positive at any of these points.

## 3. Proofs.

3.1. Proof of Theorem A. We follow Bettiol's construction of metrics of positive distance curvature on $S^{2} \times S^{2}$ [2, Theorem], [3, Theorem 6.1], and apply a first-order conformal deformation to Wilking's metric $\left(S^{2} \times S^{3}, g_{W}\right)$ that was described in Section 2.1. This yields metrics of positive distance curvature as in Definition 2, which converge to a metric $g^{0}$ as $\theta$ tends to zero in the $C^{k}$-topology.

Definition 3. Let $(M, g)$ be a compact Riemannian manifold, then, for any function $\phi: M \rightarrow \mathbb{R}$, and for any small enough $s>0$, the following is also a Riemannian metric on $M$

$$
\begin{equation*}
g_{s}=(1+s \phi) g \tag{3.1}
\end{equation*}
$$

called the first-order conformal deformation of $g$.
The variation of sectional curvature of a metric under the first order conformal deformation is given by the following lemma [9]; cf. [3, Chapter 3, Corollary 3.4].

Lemma 1. Let $(M, g)$ be a Riemannian manifold with sectional curvature $\sec _{g} \geq 0$, and let $X, Y \in T_{p} M$ be g-orthonormal vectors such that $\sec _{g}(X \wedge$ $Y)=0$. Consider a first-order conformal deformation $g_{s}=(1+s \phi) g$ of $g$. The first variation of $\sec _{g_{s}}(X \wedge Y)$ is

$$
\begin{equation*}
\left.\frac{\mathrm{d}}{\mathrm{~d} s} \sec _{g_{s}}(X \wedge Y)\right|_{s=0}=-\frac{1}{2} \operatorname{Hess} \phi(X, X)-\frac{1}{2} \operatorname{Hess} \phi(Y, Y) \tag{3.2}
\end{equation*}
$$

We will also need the following elementary fact [3, Chapter 3, Lemma 3.5].
Lemma 2. Let $f:[0, S] \times K \rightarrow \mathbb{R}$ be a smooth function, where $S>0$ and $K$ is a compact subset of a manifold. Assume that $f(0, x) \geq 0$ for all $x \in K$, and $\frac{\partial f}{\partial s}>0$ if $f(0, x)=0$. Then there exists $s_{*}>0$ such that $f(s, x)>0$ for all $x \in K$ and $0<s<s_{*}$.

Wilking's metric ( $S^{2} \times S^{3}, g_{W}$ ) has positive sectional curvature away from a hypersurface $Z$; see the discussion at the end of Section 2.1. The biorthogonal and distance curvatures are positive inside $Z$ except for points that lie in four disjoint copies of $S^{2}$. Every point in these four 2 -spheres carries an $S^{1}$ worth of flat 2 -planes. Denote these four 2 -spheres by

$$
\begin{equation*}
\left\{S_{i}^{2}: i=1,2,3,4\right\} \tag{3.3}
\end{equation*}
$$

We only deform Wilking's metric near these four submanifolds. Let

$$
\begin{equation*}
\chi_{i}: S^{2} \times S^{3} \rightarrow \mathbb{R} \tag{3.4}
\end{equation*}
$$

denote a bump function of $S_{i}^{2}$, i.e., a nonnegative function that is identically zero outside a tubular neighborhood of $S_{i}^{2}$, and identically one in a smaller tubular neighborhood of $S_{i}^{2}$. Finally, we define four functions

$$
\begin{equation*}
\left\{\psi_{i}: S^{2} \times S^{3} \rightarrow \mathbb{R}: i=1,2,3,4\right\} \tag{3.5}
\end{equation*}
$$

as

$$
\begin{equation*}
\psi_{i}(p)=\operatorname{dist}_{g_{W}}\left(p, S_{i}^{2}\right)^{2} \tag{3.6}
\end{equation*}
$$

for $p \in S^{2} \times S^{3}$, where dist $g_{W}$ is the metric distance function on $\left(S^{2} \times S^{3}, g_{W}\right)$. Let $\phi: S^{2} \times S^{3} \rightarrow \mathbb{R}$ be a function defined as

$$
\begin{equation*}
\phi=-\chi_{1} \psi_{1}-\chi_{2} \psi_{2}-\chi_{3} \psi_{3}-\chi_{4} \psi_{4}, \tag{3.7}
\end{equation*}
$$

and consider the first-order conformal deformation of $g_{W}$ given by

$$
\begin{equation*}
g_{s}=(1+s \phi) g_{W} . \tag{3.8}
\end{equation*}
$$

Note that at a point $p \in S_{i}^{2}$, we have

$$
\begin{equation*}
\operatorname{Hess} \phi(X, X)=-\operatorname{Hess} \psi_{i}(X, X)=-2 g_{W}\left(X_{\perp}, X_{\perp}\right)^{2}=-2\left\|X_{\perp}\right\|_{g_{W}}^{2} \tag{3.9}
\end{equation*}
$$

where $X_{\perp}$ denotes the component of $X$ perpendicular to $S_{i}^{2}$. For each $\theta>0$, consider the compact subset of $\left(S^{2} \times S^{3}\right) \times \operatorname{Gr}_{2}\left(T\left(S^{2} \times S^{3}\right)\right) \times \operatorname{Gr}_{2}\left(T\left(S^{2} \times S^{3}\right)\right)$ given by

$$
\begin{equation*}
K_{\theta}:=\left\{\left(p, \sigma, \sigma^{\prime}\right): \sigma, \sigma^{\prime} \in \operatorname{Gr}_{2}\left(T_{p}\left(S^{2} \times S^{3}\right)\right), \operatorname{dist}\left(\sigma, \sigma^{\prime}\right) \geq \theta\right\} \tag{3.10}
\end{equation*}
$$

and define

$$
\begin{align*}
f & :[0, S] \times K_{\theta} \rightarrow \mathbb{R} \\
f\left(s,\left(p, \sigma, \sigma^{\prime}\right)\right) & :=\frac{1}{2}\left(\sec _{g_{s}}(\sigma)+\sec _{g_{s}}\left(\sigma^{\prime}\right)\right) \tag{3.11}
\end{align*}
$$

Notice that $f\left(0,\left(p, \sigma, \sigma^{\prime}\right)\right) \geq 0$ since $^{\sec _{g_{s}} \geq 0}$. Furthermore, $f\left(0,\left(p, \sigma, \sigma^{\prime}\right)\right)=0$ only for

$$
\begin{equation*}
p \in S_{1}^{2} \cup S_{2}^{2} \cup S_{3}^{2} \cup S_{4}^{2} \tag{3.12}
\end{equation*}
$$

since these are the only points of $S^{2} \times S^{3}$ that have vanishing biorthogonal and distance curvatures. Let $\left(p, \sigma, \sigma^{\prime}\right)$ be such that $f\left(0,\left(p, \sigma, \sigma^{\prime}\right)\right)=0$ and let $\sigma=X \wedge Y$ and $\sigma^{\prime}=Z \wedge W$, where $X, Y$ are $g_{W}$-orthonormal, and $Z, W$ are $g_{W}$-orthonormal. Then, by Lemma 1 and equation (3.9), at these points of $K_{\theta}$, we have

$$
\begin{align*}
\left.\frac{\partial f}{\partial s}\right|_{s=0} & =\left.\frac{\mathrm{d}}{\mathrm{~d} s}\left(\sec _{g_{s}}(X \wedge Y)+\sec _{g_{s}}(Z \wedge W)\right)\right|_{s=0} \\
& =-\frac{1}{2} \operatorname{Hess} \phi(X, X)-\frac{1}{2} \operatorname{Hess} \phi(Y, Y)-\frac{1}{2} \operatorname{Hess} \phi(Z, Z)-\frac{1}{2} \operatorname{Hess} \phi(W, W) \\
& =\left\|X_{\perp}\right\|_{g_{W}}^{2}+\left\|Y_{\perp}\right\|_{g_{W}}^{2}+\left\|Z_{\perp}\right\|_{g_{W}}^{2}+\left\|W_{\perp}\right\|_{g_{W}}^{2}>0 . \tag{3.13}
\end{align*}
$$

The previous expression is strictly greater than zero. Indeed, since $X \wedge Y$ and $Z \wedge W$ are different 2-planes, $\operatorname{span}\{X, Y, Z, W\}$ is at least three-dimensional while the submanifolds (3.3) are two-dimensional. Hence, at least one of the perpendicular components $X_{\perp}, Y_{\perp}, Z_{\perp}, W_{\perp}$ is nonzero and (3.13) is greater
than zero. Since the assumptions of Lemma 2 for the function (3.11) are satisfied, we conclude that there is an $s_{*}$ such that $f\left(s,\left(p, \sigma, \sigma^{\prime}\right)\right)>0$ for all $\left(p, \sigma, \sigma^{\prime}\right) \in K_{\theta}$ and $0<s<s_{*}$. This is precisely the condition $\sec _{g_{s}}^{\theta}>0$ of item (a) of Theorem A. The claims of item (b) and item (c) follow from our construction; cf. [2]. The claim of item (d) follows from [2, Proposition 4.1]. As Bettiol observed in his construction of metrics of positive distance curvature on $S^{2} \times S^{2}$ [2, Section 4.4], for every $\theta>0$, there are 2-planes in $\left(S^{2} \times S^{3}, g^{\theta}\right)$ with negative sectional curvature. This completes the proof of Theorem A.

Remark 1. The metrics ( $S^{2} \times S^{3}, g^{\theta}$ ) of positive distance curvature can be made invariant under the action of certain Deck transformations including the product $\mathbb{Z} / 2 \oplus \mathbb{Z} / 2$-action. Indeed, it is possible to perform a local conformal deformation on the orbit space $\left(\mathbb{R} P^{2} \times \mathbb{R} P^{3}, g_{W}\right)$ equipped with Wilking's metric of almost positive curvature, and a similar statement to Theorem A holds for $\left(\mathbb{R} P^{2} \times \mathbb{R} P^{3}, g^{\theta}\right)$; cf. [2, Section 4.6].
3.2. Proof of Corollary B. We will use a case of the classification up to diffeomorphism of simply connected 5 -manifolds with vanishing second StiefelWhitney class due to Smale [8, Theorem A].

Theorem 1. A closed simply connected 5-manifold $M$ with torsion-free homology $H_{2}(M ; \mathbb{Z})=\mathbb{Z}^{k}$ and zero second Stiefel-Whitney class $w_{2}(M)=0$ is determined up to diffeomorphism by its second Betti number $b_{2}(M)$. In particular, $M$ is diffeomorphic to a connected sum

$$
\begin{equation*}
\left\{S^{5} \# k\left(S^{2} \times S^{3}\right): k=b_{2}(M)\right\} \tag{3.14}
\end{equation*}
$$

Theorem A and Bettiol's result regarding the positivity of biorthogonal curvature under connected sums [3, Proposition 7.11] imply that every 5-manifold in the set (3.14) admits a Riemannian metric of positive biorthogonal curvature.

Remark 2. It is natural to ask if the hypothesis $w_{2}(M)=0$ of Corollary B can be removed. Barden has shown that a closed simply connected 5 -manifold with torsion-free second homology group is diffeomorphic to a connected sum of copies of $S^{2} \times S^{3}$ and the total space $S^{3} \widetilde{\times} S^{2}$ of the nontrivial 3-sphere bundle over the 2 -sphere [1]. It is currently unknown if there is a metric of almost-positive sectional curvature on $S^{3} \widetilde{\times} S^{2}$. Unlike $S^{2} \times S^{3}$, the nontrivial bundle does not arise as a biquotient that satisfies the symmetry hypothesis needed to apply Wilking's doubling trick; see DeVito's classification of free circle actions on $S^{3} \times S^{3}$ in [5].
3.3. Proof of Proposition C. The symmetric space metric on $\mathrm{SU}(3) / \mathrm{SO}(3)$ is the metric that makes the canonical surjection

$$
\begin{align*}
\pi: \mathrm{SU}(3) & \rightarrow \mathrm{SU}(3) / \mathrm{SO}(3), \\
u & \mapsto u \mathrm{SO}(3), \tag{3.15}
\end{align*}
$$

into a Riemannian submersion, where $\mathrm{SU}(3)$ is equipped with a bi-invariant metric. The left action of $\mathrm{SU}(3)$ on $\mathrm{SU}(3) / \mathrm{SO}(3)$ induced from the left multiplication on $\mathrm{SU}(3)$ by (3.15) is transitive and isometric for the symmetric space
metric. This means that we can study curvature at one point of $\mathrm{SU}(3) / \mathrm{SO}(3)$ and isometrically translate the results to any other point. The Cartan decomposition that corresponds to $\mathrm{SU}(3) / \mathrm{SO}(3)$

$$
\begin{equation*}
T_{e} \mathrm{SU}(3) \simeq \mathfrak{s u}(3)=\mathfrak{s o}(3) \oplus \mathfrak{s o}(3)^{\perp} \tag{3.16}
\end{equation*}
$$

is orthogonal with respect to the bi-invariant metric and it is precisely the decomposition of $T_{e} \mathrm{SU}(3)$ into vertical and horizontal subspaces of the Riemannian submersion (3.15). Hence, we have

$$
\begin{equation*}
T_{\mathrm{SO}(3)}(\mathrm{SU}(3) / \mathrm{SO}(3)) \simeq \mathfrak{s o}(3)^{\perp} . \tag{3.17}
\end{equation*}
$$

To conclude that $\mathrm{SU}(3) / \mathrm{SO}(3)$ has positive biorthogonal curvature, we need to show that no two flat 2-planes are orthogonal to each other. A result of Tapp [10, Theorem 1.1] implies that a 2-plane on $\mathrm{SU}(3) / \mathrm{SO}(3)$ is flat if and only if its horizontal lift is flat. Thus, it is enough to consider horizontal flat 2-planes at the identity of $\mathrm{SU}(3)$.
 and only if $[X, Y]=0$. Since the maximal number of linearly independent commuting matrices in $\mathfrak{s u}(3)$ is two, every horizontal flat 2-plane corresponds to a maximal abelian subalgebra of $\mathfrak{s o}(3)^{\perp}$

$$
\begin{equation*}
\operatorname{span}_{\mathbb{R}}\{X, Y\}=\mathfrak{a}_{0} \subset \mathfrak{s o}(3)^{\perp} \tag{3.18}
\end{equation*}
$$

By a fundamental fact about the Cartan decomposition, see [7, Proposition $7.29]$ for the precise statement, any two maximal abelian subalgebras of $\mathfrak{s o}(3)^{\perp}$ are conjugate by an element of $\mathrm{SO}(3)$. This means that by fixing one maximal abelian subalgebra, or one horizontal flat 2-plane, we can parametrize all horizontal flat 2-planes by $\mathrm{SO}(3)$. In what follows, we will obtain an explicit parametrization of horizontal flat 2-planes at the identity of $\mathrm{SU}(3)$, and so a parametrization of flat 2-planes at a point of $\mathrm{SU}(3) / \mathrm{SO}(3)$ by choosing a basis for $\mathfrak{s u}(3)$, fixing a horizontal flat 2-plane and parametrizing $\mathrm{SO}(3)$ by Euler angles. We use this explicit parametrization to show that no two flat 2-planes can be orthogonal. For the basis of $\mathfrak{s u}(3)$, we choose $\left\{-i \lambda_{i}\right\}_{i=1, \ldots, 8}$, where the $\lambda_{i}$ 's are traceless, self-adjoint 3 by 3 matrices known as the Gell-Mann matrices [6]. The scalar product on $\mathfrak{s u}(3)$ that corresponds to the bi-invariant metric is

$$
\begin{equation*}
\langle X, Y\rangle=-\frac{1}{2} \operatorname{Tr}(X Y) \tag{3.19}
\end{equation*}
$$

for $X, Y \in \mathfrak{s u}(3)$ and the basis $\left\{-i \lambda_{i}\right\}_{i=1, \ldots, 8}$ is orthonormal with respect to (3.19). The Cartan decomposition (3.16) in this basis is

$$
\begin{equation*}
\mathfrak{s o}(3)=\operatorname{span}_{\mathbb{R}}\left\{-i \lambda_{2},-i \lambda_{5},-i \lambda_{7}\right\} \tag{3.20}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathfrak{s o}(3)^{\perp}=\operatorname{span}_{\mathbb{R}}\left\{-i \lambda_{1},-i \lambda_{3},-i \lambda_{4},-i \lambda_{6},-i \lambda_{8}\right\} . \tag{3.21}
\end{equation*}
$$

Matrices $\lambda_{3}$ and $\lambda_{8}$ are diagonal, so we use $-\lambda_{3} \wedge \lambda_{8}$ for the reference horizontal
 that $[X, Y]=0$, can now be written as

$$
\begin{equation*}
X \wedge Y=-\operatorname{Ad}_{r}\left(\lambda_{3} \wedge \lambda_{8}\right) \tag{3.22}
\end{equation*}
$$

for some $r \in \mathrm{SO}(3)$. Suppose that $X \wedge Y$ and $X^{\prime} \wedge Y^{\prime}$ are two such 2-planes with $X \wedge Y$ given by (3.22) and $X^{\prime} \wedge Y^{\prime}$ by

$$
\begin{equation*}
X^{\prime} \wedge Y^{\prime}=-\operatorname{Ad}_{r^{\prime}}\left(\lambda_{3} \wedge \lambda_{8}\right) \tag{3.23}
\end{equation*}
$$

for some $r^{\prime} \in \mathrm{SO}(3)$. For the 2-planes (3.22) and (3.23) to be orthogonal, it is necessary and sufficient that the equations

$$
\begin{align*}
& \left\langle\operatorname{Ad}_{r} \lambda_{3}, \operatorname{Ad}_{r^{\prime}} \lambda_{3}\right\rangle=0  \tag{3.24}\\
& \left\langle\operatorname{Ad}_{r} \lambda_{3}, \operatorname{Ad}_{r^{\prime}} \lambda_{8}\right\rangle=0  \tag{3.25}\\
& \left\langle\operatorname{Ad}_{r} \lambda_{8}, \operatorname{Ad}_{r^{\prime}} \lambda_{3}\right\rangle=0 \tag{3.26}
\end{align*}
$$

and

$$
\begin{equation*}
\left\langle\operatorname{Ad}_{r} \lambda_{8}, \operatorname{Ad}_{r^{\prime}} \lambda_{8}\right\rangle=0 \tag{3.27}
\end{equation*}
$$

hold. Using the Ad-invariance of the bi-invariant metric, equations (3.24), (3.25), (3.26), and (3.27) can be rewritten as

$$
\begin{align*}
& \left\langle\lambda_{3}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{3}\right\rangle=0,  \tag{3.28}\\
& \left\langle\lambda_{3}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{8}\right\rangle=0,  \tag{3.29}\\
& \left\langle\lambda_{8}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{3}\right\rangle=0, \tag{3.30}
\end{align*}
$$

and

$$
\begin{equation*}
\left\langle\lambda_{8}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{8}\right\rangle=0 \tag{3.31}
\end{equation*}
$$

We now use the Euler angle parametrization of $\mathrm{SO}(3)$ to write $r^{-1} r^{\prime} \in \mathrm{SO}(3)$ as

$$
\begin{equation*}
r^{-1} r^{\prime}=\exp \left(-i \lambda_{2} x\right) \exp \left(-i \lambda_{5} y\right) \exp \left(-i \lambda_{2} z\right) \tag{3.32}
\end{equation*}
$$

where $x, y, z \in \mathbb{R}$. Plugging (3.32) into equations (3.28), (3.29), (3.30), and (3.31) and calculating the traces explicitly, we find

$$
\begin{align*}
0 & =\left\langle\lambda_{3}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{3}\right\rangle \\
& =\frac{1}{4} \cos (2 x)(3+\cos (2 y)) \cos (2 z)-\sin (2 x) \cos (y) \sin (2 z)  \tag{3.33}\\
0 & =\left\langle\lambda_{3}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{8}\right\rangle=-\frac{\sqrt{3}}{2} \cos (2 x) \sin ^{2}(y)  \tag{3.34}\\
0 & =\left\langle\lambda_{8}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{3}\right\rangle=-\frac{\sqrt{3}}{2} \cos (2 z) \sin ^{2}(y), \tag{3.35}
\end{align*}
$$

and

$$
\begin{equation*}
0=\left\langle\lambda_{8}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{8}\right\rangle=\frac{1}{4}(1+3 \cos (2 y)) \tag{3.36}
\end{equation*}
$$

Equations (3.34), (3.35), and (3.36) imply $\cos ^{2}(y)=1 / 3$ and $\cos (2 x)=$ $\cos (2 z)=0$. Plugging this into equation (3.33), we obtain

$$
\begin{equation*}
\left\langle\lambda_{3}, \operatorname{Ad}_{r^{-1} r^{\prime}} \lambda_{3}\right\rangle \neq 0 \tag{3.37}
\end{equation*}
$$

and conclude that there is no solution to the system given by equations (3.33), (3.34), (3.35), and (3.36). This shows that no two 2-flat planes are orthogonal.

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